

$$\begin{aligned}
g &= 9.80 \frac{m}{s^2} & I &= \sum_i m_i r_i^2 \\
\bar{v} &= \frac{x_2 - x_1}{t_2 - t_1} = \frac{\Delta x}{\Delta t} & I_{disc} &= \frac{1}{2} MR^2 \\
\bar{a} &= \frac{v_2 - v_1}{t_2 - t_1} = \frac{\Delta v}{\Delta t} & I_{sphere} &= \frac{2}{5} MR^2 \\
v &= v_0 + at & I_{ring} &= MR^2 \\
x &= x_0 + v_0 t + \frac{1}{2} at^2 & \vec{\tau} &= \vec{r} \times \vec{F} \\
v^2 &= v_0^2 + 2a(x - x_0) & \sum \vec{\tau} &= I\alpha \\
x - x_0 &= \frac{1}{2}(v + v_0)t & K_{rot} &= \frac{1}{2} I\omega^2 \\
x &= x_0 + v_{x0} t & \vec{L} &= \vec{r} \times \vec{p} \\
v_x &= v_{x0} & L &= I\omega \\
y &= y_0 + v_{y0} t - \frac{1}{2} gt^2 & L_i &= L_f \\
v_y &= v_{y0} - gt & x(t) &= A \cos(\omega t) \\
v_y^2 &= v_{y0}^2 - 2g(y - y_0) & v(t) &= -\omega A \sin(\omega t) \\
\Sigma \vec{F} &= m \vec{a} & a(t) &= -\omega^2 A \cos(\omega t) \\
F_{fr} &\leq \mu_s F_N & \omega &= \sqrt{\frac{k}{m}} \\
F_{fr} &= \mu_k F_N & T &= \frac{2\pi}{\omega} \\
a_R &= \frac{v^2}{r} & f &= \frac{1}{T} \\
\vec{A} &= A_x \hat{i} + A_y \hat{j} + A_z \hat{k} & T &= 2\pi \sqrt{\frac{l}{g}} \\
A &= \sqrt{A_x^2 + A_y^2 + A_z^2} & y(x, t) &= A \sin(kx \pm \omega t) \\
\vec{A} \cdot \vec{B} &= AB \cos \theta = A_x B_x + A_y B_y + A_z B_z & k &= \frac{2\pi}{\lambda} \\
W &= \vec{F} \cdot \vec{d} & v &= \frac{\omega}{k} \\
K &= \frac{1}{2} m v^2 & v &= \sqrt{\frac{F_T}{\mu}} \\
W_{net} &= K_f - K_i & P_{avg} &= \frac{1}{2} \mu \omega^2 A^2 v \\
W_{nc} &= \Delta PE + \Delta K & f_n &= n \frac{v}{2L}, \quad n \frac{v}{4L} \\
PE_g &= mgh \\
PE_s &= \frac{1}{2} k x^2 \\
M \vec{r}_{cm} &= \sum_i m_i \vec{r}_i \\
\vec{p} &= m \vec{v} \\
v'_B - v'_A &= -(v_B - v_A) \\
\omega &= \omega_0 + \alpha t \\
\theta &= \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2 \\
\omega^2 &= \omega_0^2 = 2\alpha(\theta - \theta_0) \\
\theta - \theta_0 &= \frac{1}{2}(\omega + \omega_0)t \\
v_t &= r\omega \\
a_t &= r\alpha \\
\end{aligned}$$