Pre-Evaluation Survey

Directions: Please answer all questions as best as you can. Be honest and clear when explaining. This sheet will not be graded.

What are the two types of turns a robot can do?

What is the difference between the two turns?

What are the advantages of each turn?

Write a quick sample code in RobotC for each type of turn. Place comments describing important lines of the code.
What parts of the robot affect how the robot turns?

What parts of the robot affect how we write a program to make the robot turn?