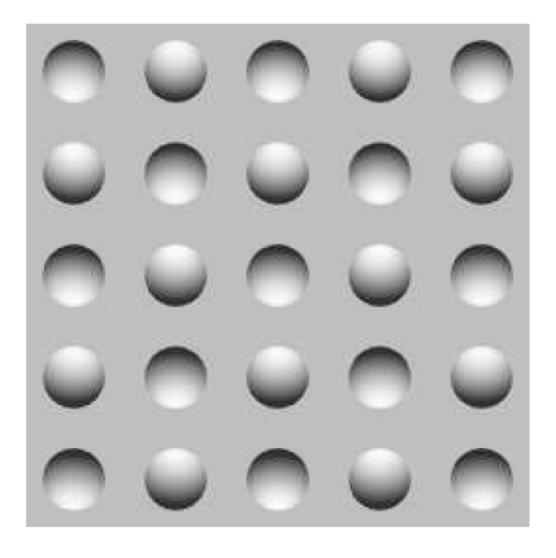


Sources, shading and photometric stereo F&P Ch 5 (old), Ch 2 (new)

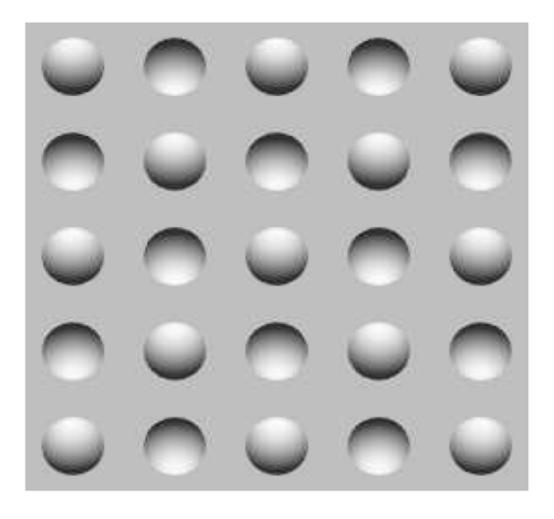
Guido Gerig CS 6643, Spring 2017

Credits: modified from original slides by David A. Forsyth plus modifications by Marc Pollefeys, Materials from Ohad Ben-Shahar, CS 202-1-5261, http://www.cs.bgu.ac.il/~ben-shahar/











Inverting the image formation process

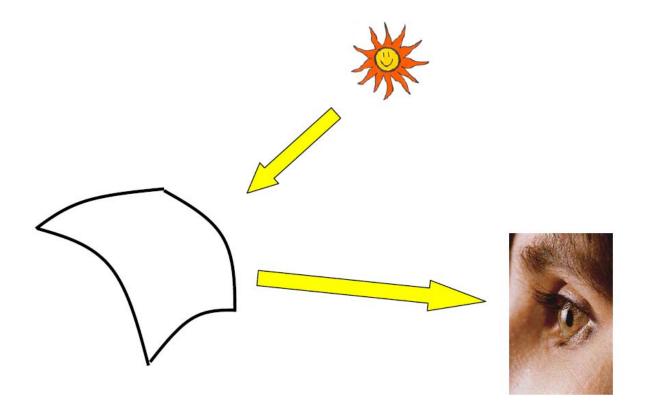


Image formation = "Shading from shape" (and light sources)

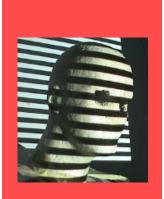
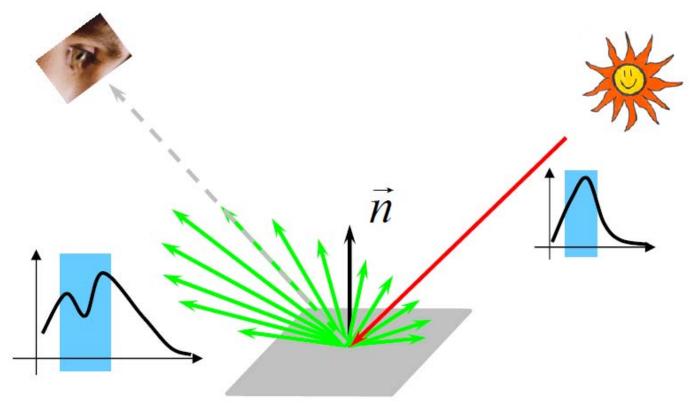
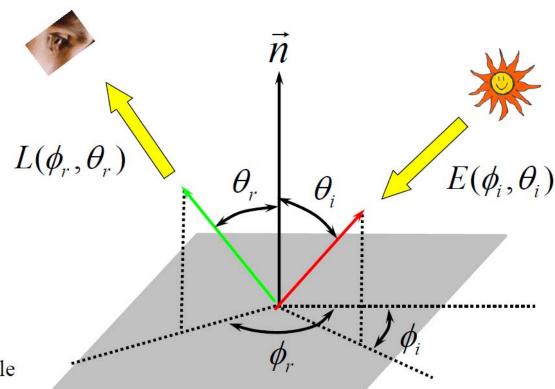


Image formation





Polar representation of directions



 ϕ - Azimuth angle

heta - Zenith angle



The Bidirectional Reflectance Distribution Function (BRDF)

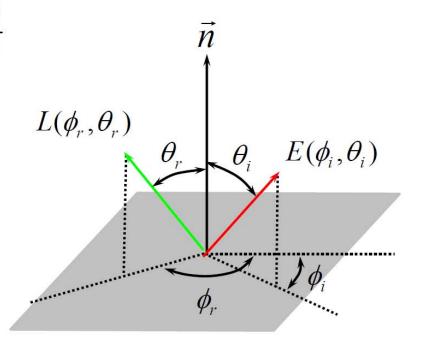
$$f_{\lambda}(\phi_{i}, \theta_{i}; \phi_{r}, \theta_{r}) = \frac{L_{\lambda}(\phi_{r}, \theta_{r})}{E_{\lambda}(\phi_{i}, \theta_{i})}$$

Helmholtz's reciprocity

$$f(\phi_i, \theta_i; \phi_r, \theta_r) = f(\phi_r, \theta_r; \phi_i, \theta_i)$$

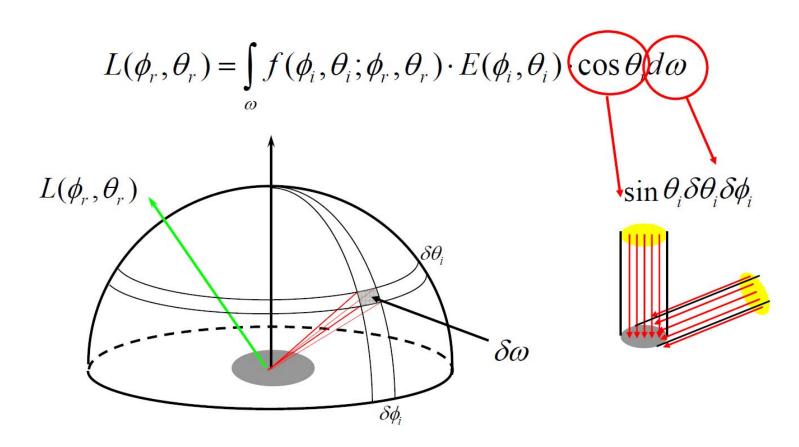
Isotropic materials:

$$f(\phi_i, \theta_i; \phi_r, \theta_r) = f(\phi_i - \phi_r, \theta_i, \theta_r)$$





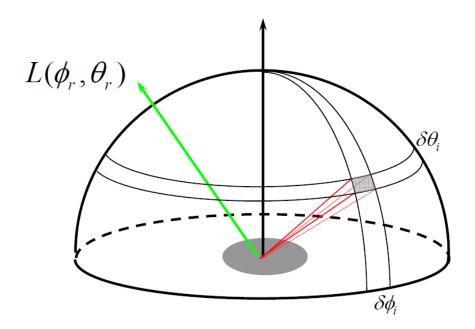
Total surface reflection





Total surface reflection

$$L(\phi_r, \theta_r) = \int_{-\pi}^{\pi} \int_{0}^{\pi/2} f(\phi_i, \theta_i; \phi_r, \theta_r) \cdot E(\phi_i, \theta_i) \cdot \sin \theta_i \cdot \cos \theta_i \cdot \delta \theta_i \delta \phi_i$$





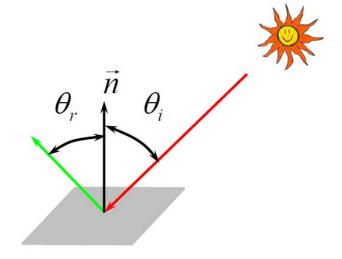
Lambertian (perfectly diffused) surfaces

$$f_{L}(\phi_{i},\theta_{i};\phi_{r},\theta_{r}) = const = \bar{f} = \rho \frac{1}{\pi}$$
Albedo



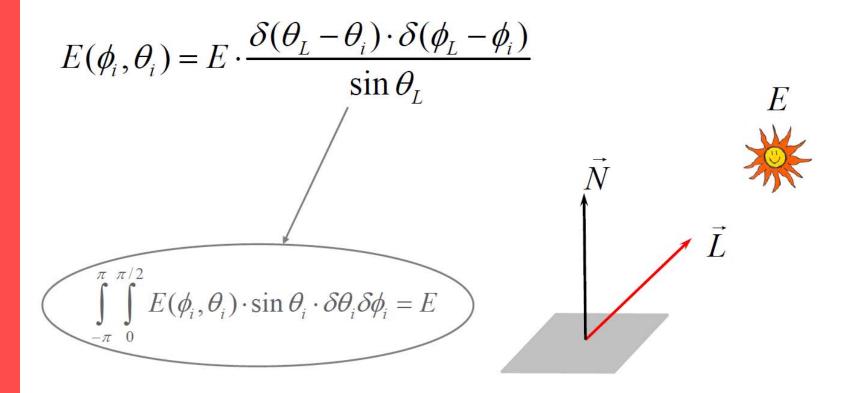
Mirrored (perfectly secular) surfaces

$$f_S(\phi_i, \theta_i; \phi_r, \theta_r) = \frac{\delta(\theta_r - \theta_i)\delta(\phi_r - \phi_i - \pi)}{\sin \theta_i \cos \theta_i}$$





Point light source from direction (ϕ_L, θ_L)





Surface brightness – appearance in the Lambertian case and point light source

$$f_{L}(\phi_{i}, \theta_{i}; \phi_{r}, \theta_{r}) = \rho \frac{1}{\pi}$$

$$E(\phi_{i}, \theta_{i}) = \frac{\delta(\theta_{L} - \theta_{i})\delta(\phi_{L} - \phi_{i})}{\sin \theta_{L}}$$

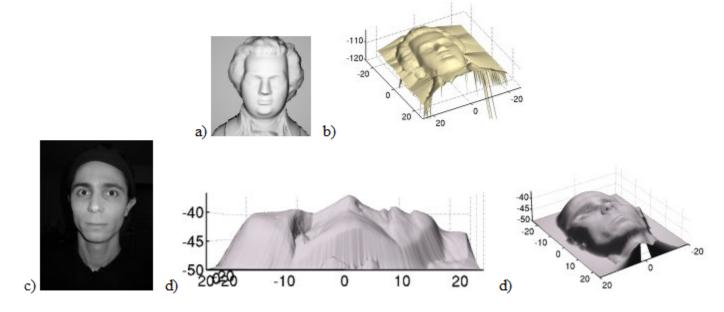
$$I(x, y) \propto L(\phi_{r}, \theta_{r}) = \int_{-\pi}^{\pi} \int_{0}^{\pi/2} f(\phi_{i}, \theta_{i}; \phi_{r}, \theta_{r}) \cdot E(\phi_{i}, \theta_{i}) \cdot \sin \theta_{i} \cdot \cos \theta_{i} \cdot \delta \theta_{i} \delta \phi_{i}$$

$$L = \rho \frac{1}{\pi} E \cos \theta_L \propto \rho(\hat{N} \cdot \hat{L})$$



Authors: Emmanuel Prados and Olivier Faugeras

CVPR'2005, International Conference on Computer Vision and Pattern Recognition, San Diego, CA, USA, June 2005.



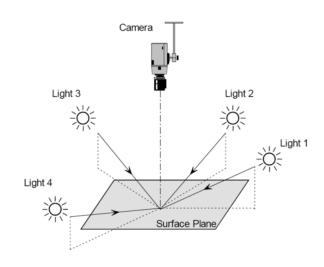
a) Synthetic image generated from the classical Mozart's face [Zhang-Tsai-etal:99]; b) reconstructed surface from a) by new algorithm; c) real image of a face; d)-e) reconstructed surface from c) by new algorithm.



Photometric stereo

Assume:

- a local shading model
- a set of point sources that are infinitely distant
- a set of pictures of an object, obtained in exactly the same camera/object configuration but using different sources
- A Lambertian object (or the specular component has been identified and removed)





Photometric Stereo Christopher Bireley



Bandage Dog





Preprocessing

- Remove background isolate dog
- Filter with NL Means







Photometric Stereo Christopher Bireley

