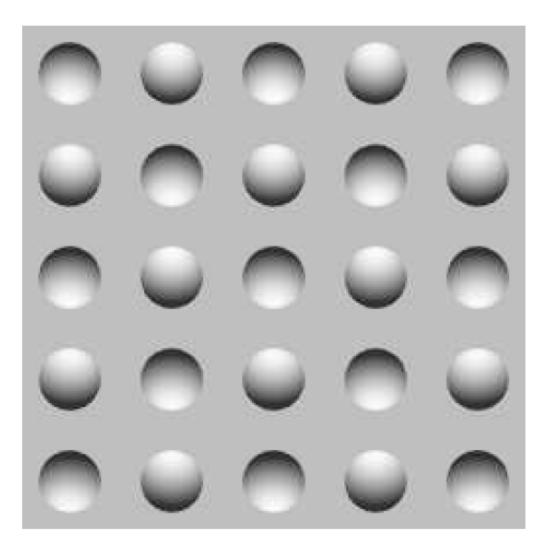


## Sources, shading and photometric stereo F&P Ch 5 (old), Ch 2 (new)

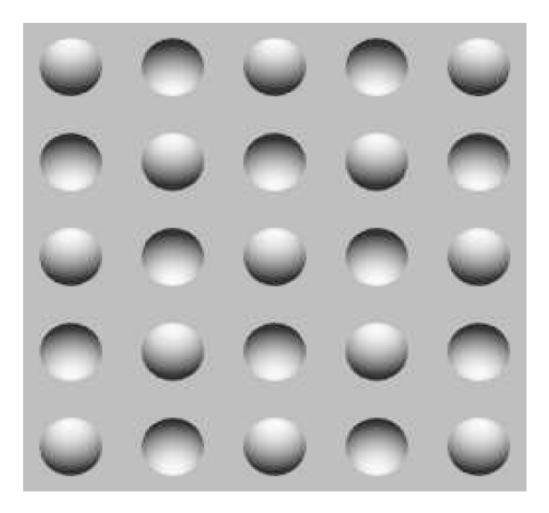
Guido Gerig CS 6643, Spring 2016

Credits: modified from original slides by David A. Forsyth plus modifications by Marc Pollefeys, Materials from Ohad Ben-Shahar, CS 202-1-5261, http://www.cs.bgu.ac.il/~ben-shahar/



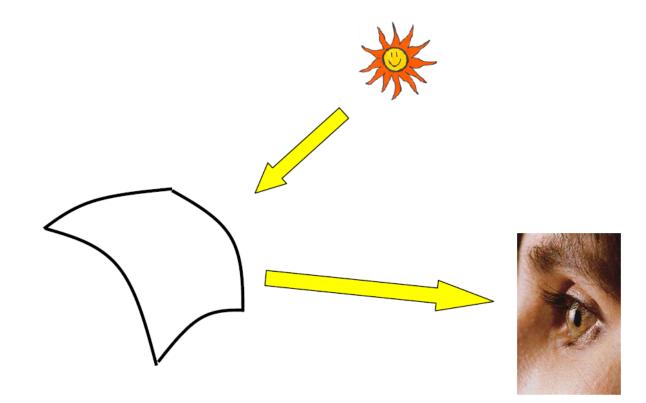








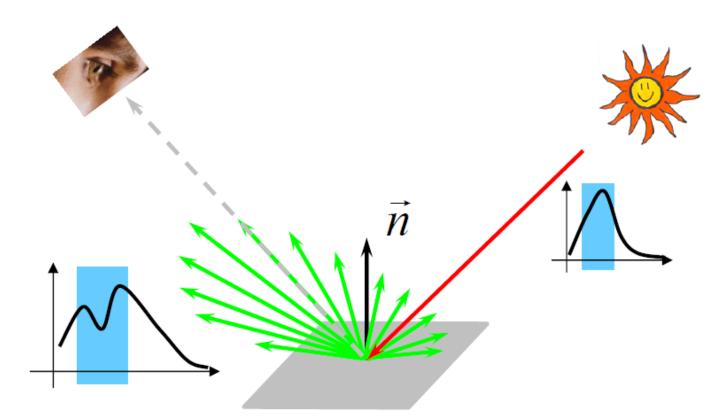
#### **Inverting the image formation process**



#### Image formation = "Shading from shape" (and light sources) Courtesy Ohad Ben-Shahar, BGU, http://www.cs.bgu.ac.il/~ben-shahar/

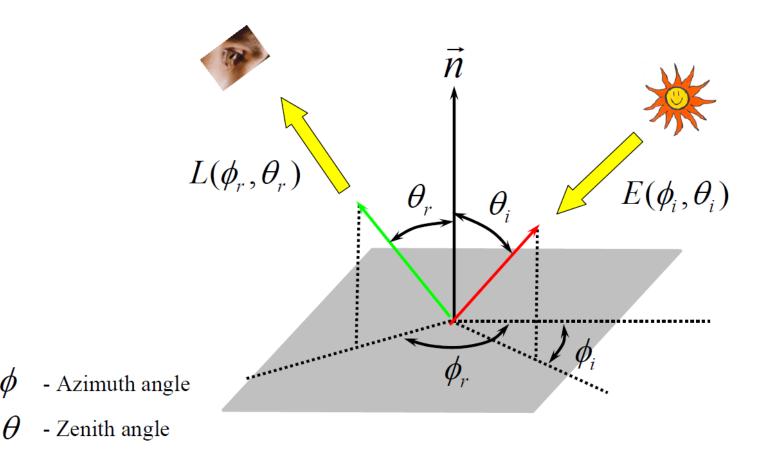


#### **Image formation**



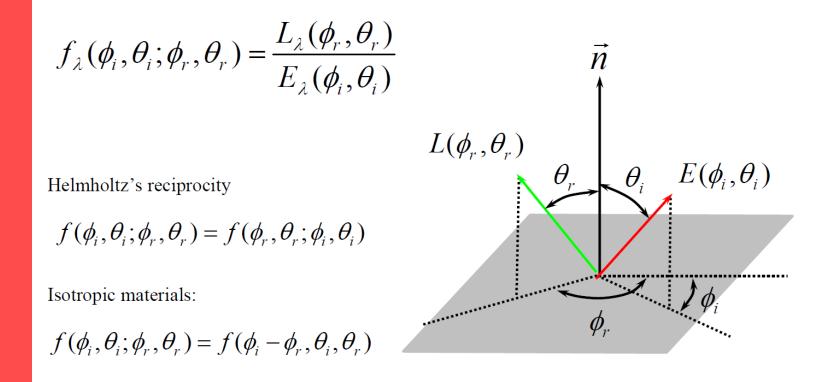


#### **Polar representation of directions**



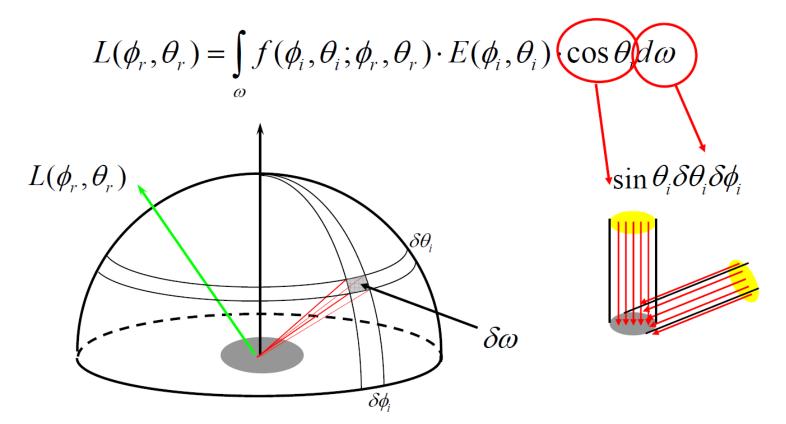


The Bidirectional Reflectance Distribution Function (BRDF)





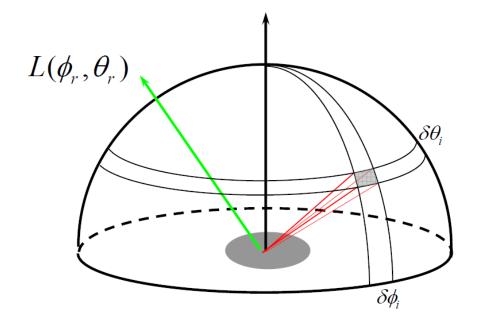
**Total surface reflection** 





**Total surface reflection** 

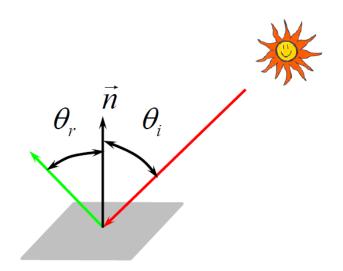
$$L(\phi_r, \theta_r) = \int_{-\pi}^{\pi} \int_{0}^{\pi/2} f(\phi_i, \theta_i; \phi_r, \theta_r) \cdot E(\phi_i, \theta_i) \cdot \sin \theta_i \cdot \cos \theta_i \cdot \delta \theta_i \delta \phi_i$$





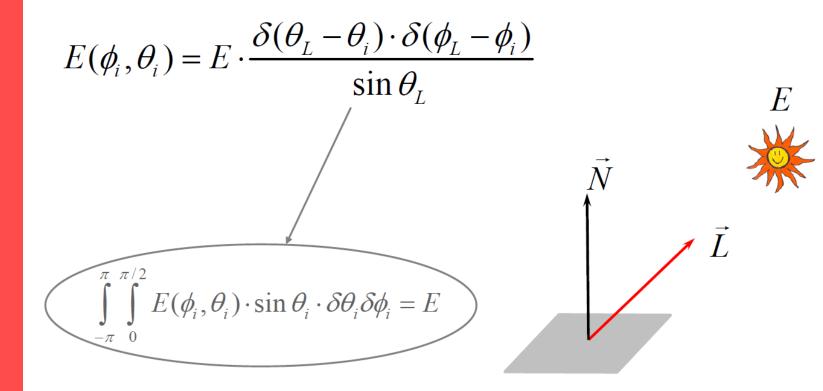
Mirrored (perfectly secular) surfaces

$$f_{S}(\phi_{i},\theta_{i};\phi_{r},\theta_{r}) = \frac{\delta(\theta_{r}-\theta_{i})\delta(\phi_{r}-\phi_{i}-\pi)}{\sin\theta_{i}\cos\theta_{i}}$$





**Point light source from direction**  $(\phi_L, \theta_L)$ 



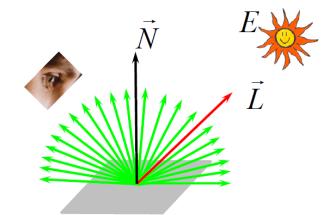


Surface brightness – appearance in the Lambertian case and point light source

$$f_{L}(\phi_{i},\theta_{i};\phi_{r},\theta_{r}) = \rho \frac{1}{\pi} \qquad E(\phi_{i},\theta_{i}) = \frac{\delta(\theta_{L}-\theta_{i})\delta(\phi_{L}-\phi_{i})}{\sin\theta_{L}}$$

$$I(x,y) \propto L(\phi_{r},\theta_{r}) = \int_{-\pi}^{\pi} \int_{0}^{\pi/2} f(\phi_{i},\theta_{i};\phi_{r},\theta_{r}) \cdot E(\phi_{i},\theta_{i}) \cdot \sin\theta_{i} \cdot \cos\theta_{i} \cdot \delta\theta_{i} \delta\phi_{i}$$

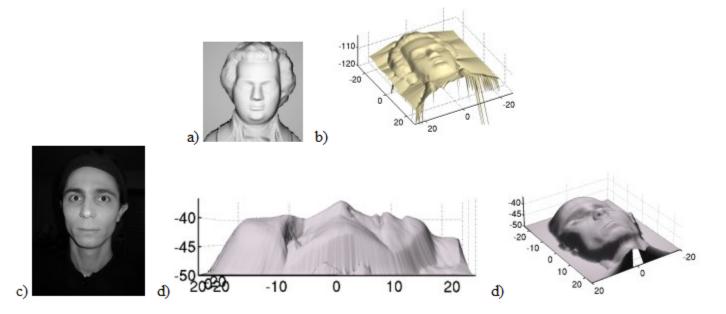
$$L = \rho \frac{1}{\pi} E \cos \theta_L \propto \rho(\hat{N} \cdot \hat{L})$$





#### Authors: Emmanuel Prados and Olivier Faugeras

CVPR'2005, International Conference on Computer Vision and Pattern Recognition, San Diego, CA, USA, June 2005.

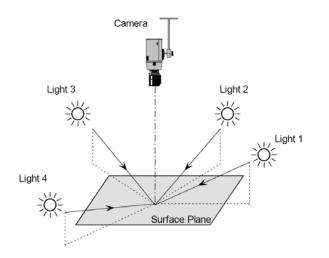


a) Synthetic image generated from the classical Mozart's face [Zhang-Tsai-etal:99]; b) reconstructed surface from a) by new algorithm; c) real image of a face; d)-e) reconstructed surface from c) by new algorithm.



#### Photometric stereo

- Assume:
  - a local shading model
  - a set of point sources that are infinitely distant
  - a set of pictures of an object, obtained in exactly the same camera/object configuration but using different sources
  - A Lambertian object (or the specular component has been identified and removed)





#### Photometric Stereo Christopher Bireley



Bandage Dog





#### Preprocessing

- Remove background isolate dog
- Filter with NL Means







#### Photometric Stereo Christopher Bireley

